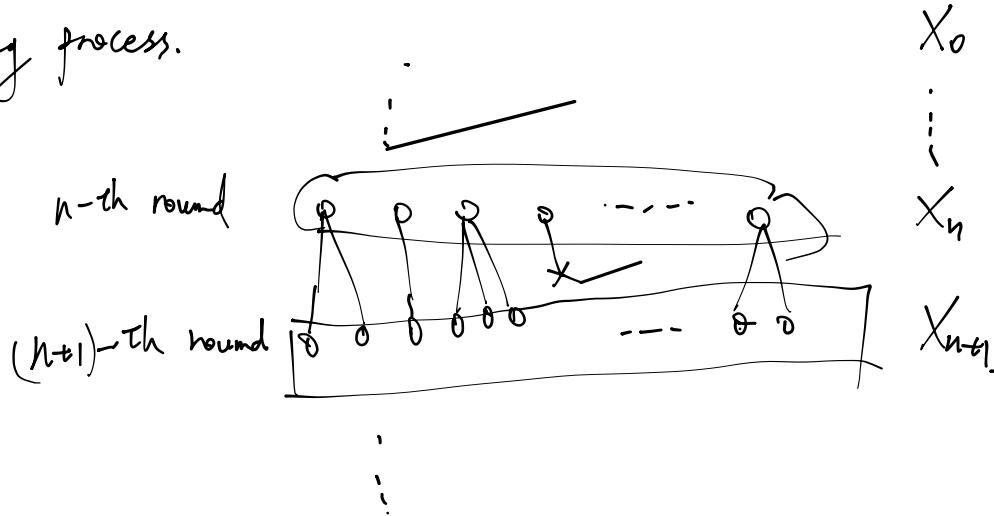


M.G. convergence $\left\{ \begin{array}{l} \mathbb{E}[X_n] < \infty, \text{ uniformly bounded from above/below} \\ \text{u.i. } \mathbb{E}[X_\infty] < \infty. \& \mathbb{E}[X_\infty] = \mathbb{E}[X_0] \\ \mathbb{E}[|X_\infty - X_n|] \rightarrow 0. \\ (\text{not covered}) \text{ For } p > 1 \quad \mathbb{E}[|X_n|^p] \leq C < \infty \\ (\text{Implies u.i.}) \quad \mathbb{E}[|X_n - X_\infty|^p] \rightarrow 0. \end{array} \right.$

Branching process.



μ = "offspring distribution" on $\{0, 1, 2, \dots\}$

$$X_{n+1} = Z_{n,1} + Z_{n,2} + \dots + Z_{n,q}$$

where $Z_{n,i}$'s are iid r.v. from μ .

$Z_{n,i}$: children of the i -th individual
in n -th round.

Question: die out or not?

$$\mathbb{E}[X_{n+1} | \mathcal{F}_n] = \sum_{i=1}^{X_n} \mathbb{E}[Z_{n,i} | \mathcal{F}_n] = X_n \cdot \mathbb{E}_\mu[Z].$$

$$m := \mathbb{E}_\mu[Z] = \sum_{i \geq 0} i \cdot \mu_i$$

$Y_n = m^{-n} X_n$ is a MG.

e.g. If $m \leq 1$, $\mathbb{E}[X_n] = m^n \cdot \mathbb{E}[X_0] \rightarrow 0$ (as $n \rightarrow \infty$)

So $X_n \xrightarrow{P} 0$.

e.g. If $m > 1$, then $\mu_0 > 0$.

w.p. > 0 the one $\mathbb{P}(X_n \rightarrow \infty) > 0$.
 $\mathbb{E}[X_n] \rightarrow \infty$.

How about $m=1$? (Assume $\mu_1 < 1$).

X_n is a MG. $X_n \geq 0$ (H1).

$$X_n \xrightarrow{\text{a.s.}} X_\infty$$

X_n integer $\Rightarrow \exists T < \infty$. a.s.
 $X_n = X_\infty$ after $n \geq T$.

So $X_n \rightarrow 0$ a.s.

Dob's martingale $\times \mathbb{E}[X] < \infty$.

$$\mathcal{F}_1 \subseteq \mathcal{F}_2 \subseteq \dots \subseteq \mathcal{F}_n \subseteq \dots$$

$$M_n = \mathbb{E}[X | \mathcal{F}_n]$$

$$\mathbb{E}[M_{n+1} | \mathcal{F}_n] = \mathbb{E}[\mathbb{E}[X | \mathcal{F}_{n+1}] | \mathcal{F}_n].$$

$$= \mathbb{E}[X | \mathcal{F}_n] = M_n.$$

Uniform integrability. $\forall \varepsilon, \exists K$ s.t.

$$\mathbb{E}[|M_n| \cdot \mathbf{1}_{\{|M_n| > K\}}] \leq \mathbb{E}[|X| \cdot \mathbf{1}_{\{|X| > K\}}] \leq \varepsilon.$$

$$X_n \xrightarrow{\mathbb{P}} X_\infty$$

$$\text{Indeed, if } \mathcal{F}_\infty = \bigcup_{n=1}^{\infty} \mathcal{F}_n \quad X_\infty = \mathbb{E}[X | \mathcal{F}_\infty].$$

e.g. Posterior consistency.

$$\theta \sim \pi \quad (\text{prior distribution})$$

$$X_1, X_2, \dots, X_n | \theta \xrightarrow{\text{iid}} p_\theta$$

$$\text{Posterior distribution} \quad \pi(\theta | X_1, X_2, \dots, X_n) \propto \pi(\theta) \cdot p_\theta(X_1) \cdots p_\theta(X_n)$$

Goal: estimate $g(\theta)$

$$\hat{g}_n := \mathbb{E}[g(\theta) | X_1, X_2, \dots, X_n].$$

$$\hat{g}_n \xrightarrow{\text{?}} g(\theta).$$

$F_n = (X_1, X_2, \dots, X_n)$ (\hat{g}_n) _{$n \geq 0$} is Prob. Ma.

$$\hat{g}_n \xrightarrow[L^1]{\text{a.s.}} g_\infty = \mathbb{E}[g(\theta) | F_\infty]$$

g_∞ is a r.v. determined by $F_\infty = (X_\delta)_{\delta=1}^{+\infty}$.

e.g. when $\exists (\tilde{g}_n)_{n \geq 1}$ s.t. $\tilde{g}_n \xrightarrow{\text{a.s.}} g(\theta)$. ($\mathbb{H}\theta$).

$g(\theta)$ can be determined by F_∞ .

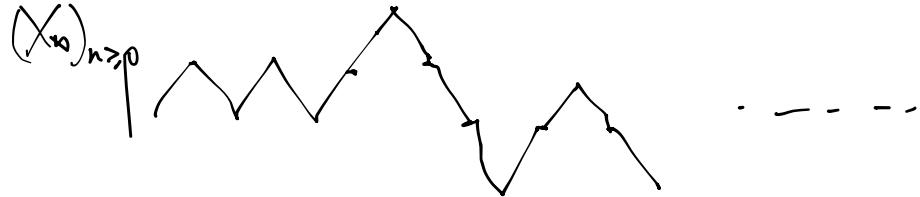
$$\mathbb{E}[g(\theta) | F_\infty] = g(\theta).$$

$$\hookrightarrow \hat{g}_n \xrightarrow{\text{a.s.}} g(\theta)$$

Brownian motion.

Moreover \vdash SRW in 1-d.

$(X_n)_{n \geq 0}$



$\varepsilon_i \stackrel{iid}{\sim} \begin{cases} +1 & \text{up} \\ -1 & \text{down} \end{cases}$

At time n .

$$X_n = \varepsilon_1 + \varepsilon_2 + \dots + \varepsilon_n$$

$$\xrightarrow[\sqrt{n}]{} X_n \xrightarrow{d} N(0, 1)$$

For finite k fixed.

$$0 < t_1 < t_2 < \dots < t_k < \infty$$

$$(X_{[nt_1]}, X_{[nt_2]}, \dots, X_{[nt_k]})$$

$$\sqrt{n} \cdot \begin{bmatrix} X_{[nt_1]} \\ X_{[nt_2]} - X_{[nt_1]} \\ X_{[nt_3]} - X_{[nt_2]} \\ \vdots \\ X_{[nt_k]} - X_{[nt_{k-1}]} \end{bmatrix} \xrightarrow{d} N\left(0, \begin{bmatrix} t_1 & t_2 - t_1 & \dots & 0 \\ 0 & t_3 - t_2 & \dots & t_{k-1} - t_{k-2} \end{bmatrix}\right).$$

$$\left(\frac{1}{\sqrt{n}} X_{[nt]} \right)_{n \in \mathbb{N}} \xrightarrow{d} \text{something.}$$

Defn. $(B_t)_{t \geq 0}$ is BM iff.

$$1. B_0 = 0$$

2. Normally distributed $B_t \sim N(0, t)$.

3. Independent normal increments.

$$\text{For } t > s, \quad B_t - B_s \sim N(0, t-s)$$

independent of $(B_t)_{0 \leq t \leq s}$.

4. (implied by 3).

$$\text{cov}(B_t, B_s) = \min(s, t).$$

$$\mathbb{E}[B_t B_s] = \underbrace{\mathbb{E}[(B_t - B_s) \cdot B_s]}_{=0} + \underbrace{\mathbb{E}[B_s^2]}_{s.}$$

5 - mapping $t \mapsto B_t$ is continuous a.s.

Invention - at time $[t, t+\Delta t]$, make increment $\sim N(0, \Delta t)$.

$$\lim_{\Delta t \rightarrow 0} \frac{B_{t+\Delta t} - B_t}{\Delta t} \sim N(0, 1) \quad |B_{t+\Delta t} - B_t| \approx \sqrt{\Delta t}$$

Limit does not exist
To prove - $\forall \epsilon, \quad P(B \text{ is non-diff at } t) = 1$.

Fact $P(\forall t \in (0, \infty), B \text{ is non-diff at } t) = 1$.

trace: B_M is Markov.

$(B_t - B_s)_{t \geq s}$ is a BM, indep of the past

"Strong Markov property".

Stopping time in obs-time case:

Def T is a stopping time if

the event $\{T \leq t\}$ is determined by

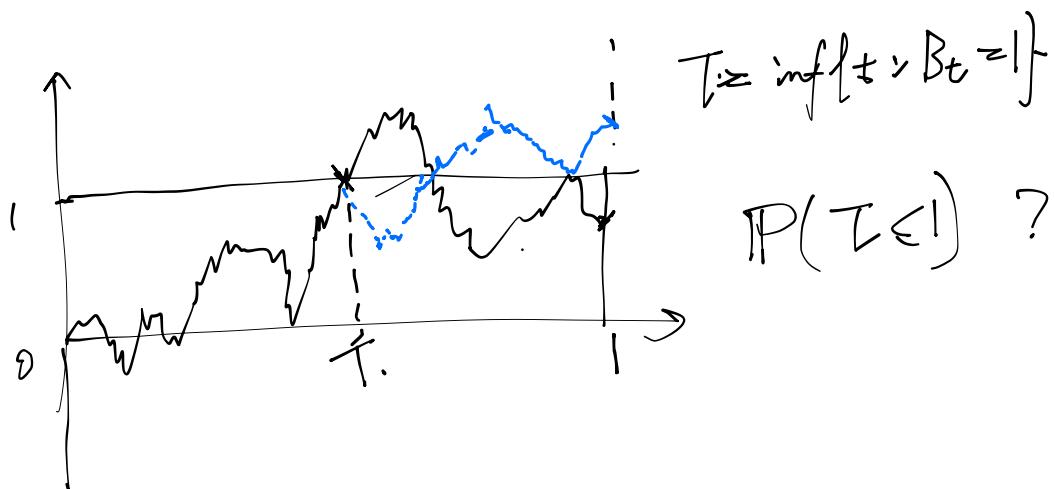
F_t , i.e. $(B_s)_{0 \leq s \leq t}$.

e.g. Hitting time of $a \in \mathbb{R}$.

Prob: T is a stopping time $\overbrace{\quad P(T < \infty) = 1}$

then $(B_{t+T} - B_T)_{t \geq 0}$ is a BM

independent of $(B_s)_{0 \leq s \leq T}$.



"Reflection principle".

At time $t=1$ $\begin{cases} B_t \leq 1 \\ B_t > 1. \quad (\text{already hit}) \end{cases}$

$$\mathbb{P}(B_1 \geq 1) = \underbrace{\mathbb{P}(\tau \leq 1)}_{\text{Computable.}} \cdot \mathbb{P}(B_1 \geq 1 \mid \tau \leq 1)$$

~~$\neq \mathbb{P}(\tau > 1) \cdot 0.$~~

Goal

By strong Markov.

$(B_t - 1)_{t \geq \tau}$ is BM.

Conditionally on $(B_t)_{0 \leq t \leq \tau}$,

$$\mathbb{P}(B_1 \geq 1 \mid (B_t)_{0 \leq t \leq \tau}, \tau \leq 1)$$

$$= \mathbb{P}(N(0, 1-t) \geq 0) = \frac{1}{2}.$$

Conclusion:

$$\begin{aligned} \mathbb{P}(\tau \leq 1) &= 2 \cdot \mathbb{P}(X_1 \geq 1) \\ &= 2 \cdot \int_1^{+\infty} \frac{1}{\sqrt{2\pi}} e^{-x^2/2} dx \end{aligned}$$

$$\mathbb{P}(\tau_a \leq t) = 2 \cdot \mathbb{P}(X_t \geq a) = 2 \int_a^{+\infty} \frac{1}{\sqrt{2\pi t}} e^{-x^2/2t} dx$$

$$\mathbb{P}(T_a < t) = \mathbb{P}\left(\max_{0 \leq s \leq t} B_s \geq a\right).$$